

<b>Module title</b>		<b>SM Code</b>
Mechanical Engineering		TM
<b>Module lecturer</b>	<b>Faculty</b>	
N.N.	Electrical Engineering and Information Technology	
<b>Module language</b>	<b>Number of SWS / WSH</b>	<b>ETCS credits</b>
English	4 SWS / WSH	5
<b>Teaching format</b>		
Seminar-based teaching with approx. 25-30% exercises		

<b>Semester according to the study plan</b>	
2 <sup>nd</sup> semester (Bachelor)	
<b>Attendance/classroom hours</b>	<b>Additional independent study</b>
56 hours	Preparation and follow-up work: 62 hours Exam preparation: 32 hours
<b>Type of examination / Requirements for the award of the credit points</b>	
Written exam: 90 minutes	

<b>Teaching content</b>
<p><b>Stereostatics:</b></p> <ul style="list-style-type: none"> <li>• Basic concepts, fundamental axioms and principles, section principle</li> <li>• Force systems on rigid bodies, center of force, center of gravity</li> <li>• Equilibrium</li> <li>• Support and joint reactions in flat structures</li> <li>• Shear reactions in ropes, rods, beams, frames, and arches</li> <li>• Coulomb friction</li> </ul>

**Elastostatics:**

- Stresses, deformations, distortions, Hooke's law
- Stresses and deformations under tensile and compressive loading
- Thermal expansion and thermal stress
- Stresses and deformations in straight bending, shear, and torsion of straight components
- Statically indeterminate systems
- Stress superposition, equivalent stress, and strength hypotheses

**Kinematics:**

- Linear and general motion of a point
- General motion of rigid bodies
- Coupled motion of systems Rigid bodies, constraints

**Kinetics:**

- Fundamental law of dynamics
- Law of momentum, law of angular momentum, law of work, and law of energy for the mass point
- Rotation of rigid bodies, moments of inertia
- Law of momentum, law of angular momentum, law of work, and law of energy for rigid bodies
- Principle of d'Alembert
- Introduction to mechanical oscillations

**Learning objective: Professional competence****After successfully completing this module, students will be able to**

- describe the basic principles of stereo- and elastostatics, the motion of mass points and rigid bodies (1)
- specify the scope of validity of the developed solutions defined by assumptions and prerequisites (2)
- create simple static equivalent models and use them to determine unknown variables (e.g., bearing and section reactions) with the help of equilibrium conditions (2)
- scale simple, statically loaded structures with regard to deformation and strength (2)

- to deal with dynamic problems by formulating and solving the basic kinematic and kinetic equations (2)
- solve simple mechanical problems independently (3)
- understand, evaluate, and discuss complex mechanical tasks (3)

## Literature

### Recommended reading

- Hahn, H. G. (1993). *Technische Mechanik*. Hanser
- Gross, D., Hauger, W., Schröder, J., & Wall, W. A. (2013). *Technische Mechanik*. Springer
- Altenbach, H. (2014). *Holzmann/Meyer/Schumpich Technische Mechanik Festigkeitslehre*. Springer

The numbers in brackets indicate the levels to be achieved: (1)-know | (2)-can | (3)-understand and apply